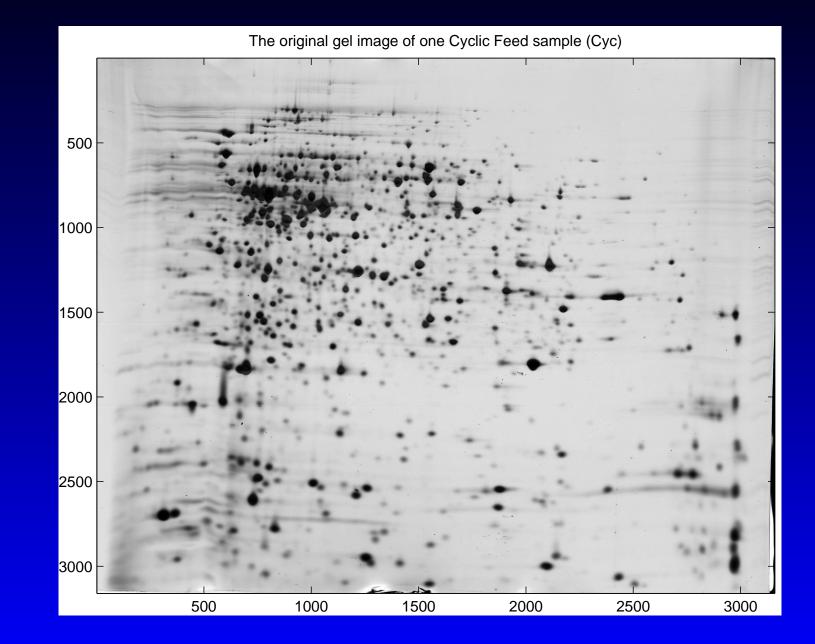
Statistical Challenges in Proteomics Making Sense of Two-Dimensional Electrophoretic Data

Françoise Seillier-Moiseiwitsch Anindya Roy Yaming Hang Florian Potra Xing Liu

Department of Mathematics & Statistics University of Maryland, Baltimore County



Outline

 Description of the Technology 2-D polyacrylamide gel electrophoresis separate thousands of proteins (> 2,000 for mammalian cell sample)

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 State-of-the-Art Analytical Methods noise reduction spot identification feature selection

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- State-of-the-Art Analytical Methods noise reduction spot identification feature selection
- Statistical Approaches spike removal streak removal gel alignment modeling

The Technology

First dimension isoelectric focusing
proteins focused electrophoretically in pH gradient
stop moving when at position with no net charge isoelectric point

Second dimension molecular mass
proteins coated with sodium dodecylsulphate (SDS)
→ same charge density
separated orthogonally by electrophoresis on polyacrylamide gel

independent dimensions

The Technology (ctd)

separated proteins stained with fluorescent dyes
image of displayed proteins = proteome
digital scanning into database

Some Challenges

- gel reproducibility same quality from day to day and from lab to lab
- losses due to hydrophobic interactions between some proteins and gel
- removal of nucleic acids streaks, artifactual migration
- low abundance protein copy number for detection on gel?

Analytical Methods

implemented in MELANIE package

• Spot detection

non-parametric method based on Laplacian and second derivatives I(x, y) = 2-D image $\mathbf{p} = (x, y) = \text{point on image}$ $S_i = \text{spot}$ T = saturation threshold $\Delta I(\mathbf{p}) = \text{Laplacian}$ $= -\left(\frac{\partial^2}{\partial x^2}I(\mathbf{p}) + \frac{\partial^2}{\partial y^2}I(\mathbf{p})\right)$

Is **p** part of a spot? l, r, c small positive thresholds • $I(\mathbf{p}) < T$

$$\mathbf{p} \in S_i \iff \min\left(\frac{\partial^2}{\partial x^2}I(\mathbf{p}) - r, \frac{\partial^2}{\partial y^2}I(\mathbf{p}) - c\right) > 0$$

when $-\Delta I(\mathbf{p}) - l \ge 0$ • $I(\mathbf{p}) > T$

$$\mathbf{p} \in S_i \iff \min\left(\frac{\partial^2}{\partial x^2}I(\mathbf{p}), \frac{\partial^2}{\partial y^2}I(\mathbf{p})\right) > 0$$

• Spot quantification

Direct method

spot area = number of pixels × pixel area spot optical density = $\max_{x,y \in \text{spot}} I(x,y)$

spot volume =
$$\sum_{x \in \text{spot}} I(x, y)$$

 $x,y \in \text{spot}$

Gaussian curve fitting

• Image alignment

polynomial image warping

 $(x,y) \rightarrow (u(x),v(y))$

(x, y) = pixel coordinates in original image (u, v) = pixel coordinates in warped image

- = 1st-, 2nd- or 3rd-order polynomials estimated via least-squares criterion
- select landmarks on each image
- choose one gel as reference
- estimate parameters by summing over landmarks

• Spot matching

- for each spot, select cluster of neighbor spots central spot = primary spot surrounding spots = secondary spots spot \in cluster if centroid in circle of fixed radius radius depends on image dimension, number of spots, minimum number of spots in cluster

 match highest-intensity clusters primary spots

- compare clusters probabilistic similarity measure: probability of next random hit within a cluster where m - 1 spots have been matched

- Spot matching (ctd)
 - consistency check for possible mismatching

$$\begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} t_x \\ t_y \end{pmatrix} + \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

check $L = AD - BC \approx 1$ rotation for each primary cluster parameters estimated from 3 matched spots $L = 1.0 \pm 0.25$ and $\theta \pm 10$ degrees $\rightarrow good match$

- transformation to match remaining spots from good matches in 2 clusters estimate A, \dots, D by least-square method

• Creating synthetic gels merge gel images to get master gel - select reference gel spot positions in reference gel = spot position in synthetic gel - check spots on reference gel well matched to spots on 2 other gels \rightarrow triangles of matched spots (= starting groups) - extend starting groups by adding spots connectivity test: spot matched with at least one other spot in initial group

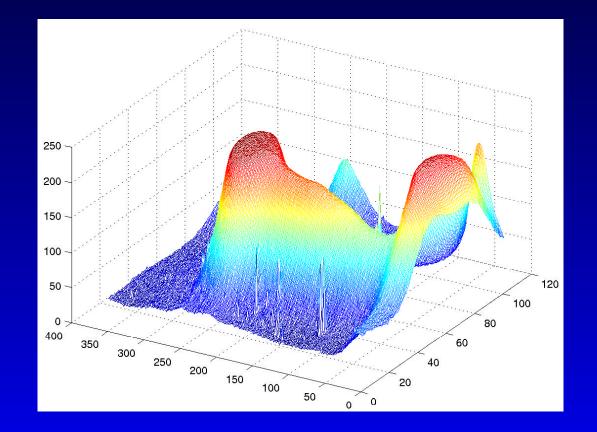
- Creating synthetic gels (ctd)
 - when all spots on reference gel considered, create additional groups with spots on 2nd gel which are not part of group and repeat with other gels
 - synthetic gel contains same number of spots as determined groups
 - representative spots
 - position: from reference gel if group has spot on reference gel closest spot + translation otherwise intensity: average for spots in group shape: shape of spot in group closest in area to average of group

- Filtering gel images
 - Gaussian smoothing
 - diffusion smoothing
 - polynomial smoothing
 - daptive smoothing
 - preserves significant discontinuities

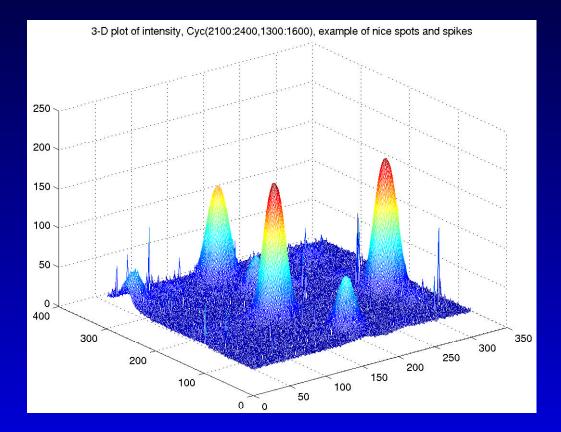
- Background filtering
 - global minimum pixel value
 - estimate background outside spots with 3rd-order polynomial

Statistical Approaches

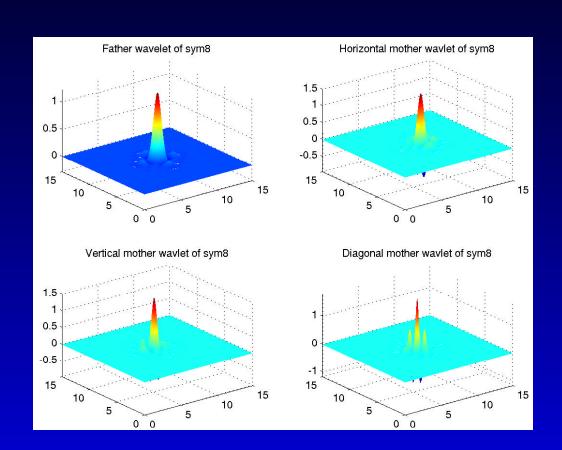
Gaussian?



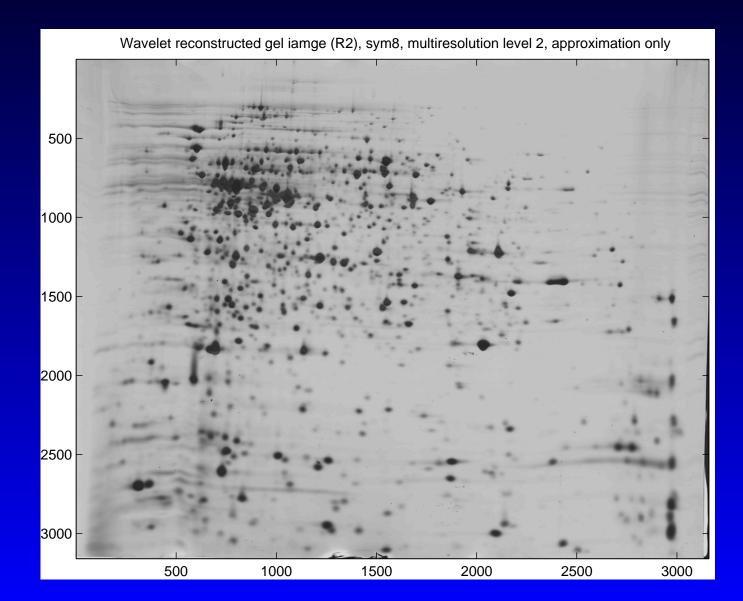
• Spike Removal



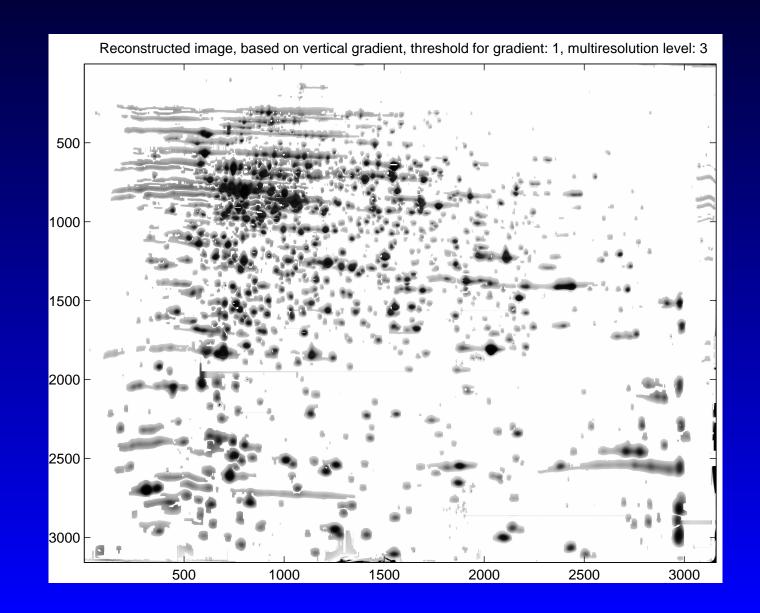
Statistical Approaches (ctd) Wavelet methods



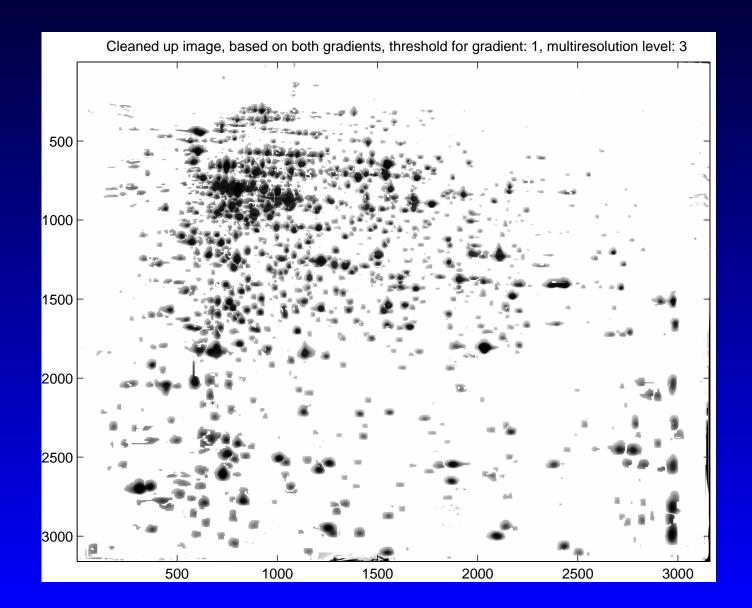
• Streak Removal



Statistical Approaches (ctd) Streak Removal (ctd)



• Streak Removal (ctd)



• Gel Alignment

N gels with M points on each gel Find transformations

 $T_i: R^2 \to R^2$, for gel i (i = 1, 2, ..., N)describing changes for all spots on the gel. Linear transformations for every gel: $T_i(x) = A_i x + b_i$, where

 $A_{i} = \begin{pmatrix} \alpha_{i} & \beta_{i} \\ \gamma_{i} & \delta_{i} \end{pmatrix}, b_{i} = \begin{pmatrix} \varphi_{i} \\ \psi_{i} \end{pmatrix}, i = 1, 2, \dots, N$

• Gel Alignment (ctd) Position of center of spot j on gel i : $l_{ij}, i = 1, 2, \dots, N, j = 1, 2, \dots, M$, i.e. $l_{ij} = \left(egin{array}{c} l_{ij}^1 \ l_{ij}^2 \ l_{ij}^2 \end{array}
ight)$ Transformed l_{ii} $\begin{pmatrix} \theta_{ij}^1\\ \theta_{ij}^2\\ \theta_{ij}^2 \end{pmatrix} = \theta_{ij} = T_i(l_{ij})$ $\theta_{ij}^1 = \alpha_i l_{ij}^1 + \beta_i l_{ij}^2 + \varphi_i$ $\theta_{ij}^2 = \gamma_i l_{ij}^1 + \delta_i l_{ij}^2 + \psi_i$ *True* location of spot $j : l_j$

• Gel Alignment (ctd)

Restriction on transformed points: – not be too far away from the true location $\|\theta_{ij} - l_i\|_{\infty} \leq \epsilon_{ij}$, i.e.

 $-\epsilon_{ij} \le \theta_{ij}^1 - l_i^1 \le \epsilon_{ij}, i = 1, 2, \dots, N, j = 1, 2, \dots, M$

 $-\epsilon_{ij} \leq \theta_{ij}^2 - l_i^2 \leq \epsilon_{ij}, i = 1, 2, \dots, N, j = 1, 2, \dots, M$

where ϵ_{ij} is a given error bound.

transformation as close as possible to identity transformation

• Gel Alignment (ctd)

Objective function:

$$\sum_{i=1}^{N} (\|A_i - I\|^2 + \|b_i\|^2)$$

+ penalty term

weighted sum distance between true location and average spot centers

Constraint: weighted sum of distances between true location and transform points

- Gel Alignment (ctd)
 - Quadratic Programming

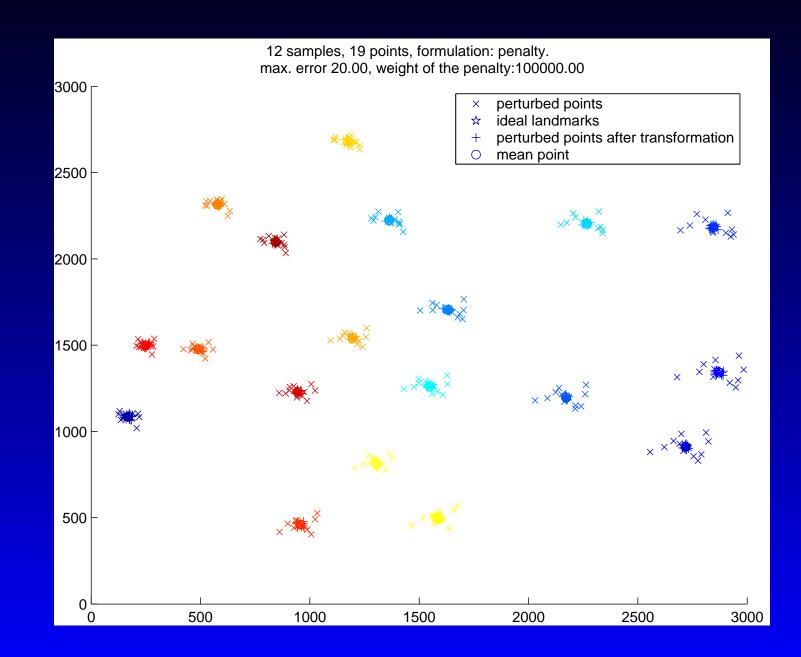
Given data l_{ij} (i = 1, 2, ..., N, j = 1, 2, ..., M), maximum allowable error ϵ_{ij} , and a weight w, first compute the mean of each spot center on different images ml_j , then solve

$$\min_{\alpha_{i},\beta_{i},\gamma_{i},\delta_{i},\varphi_{i},\psi_{i},l_{j}} \sum_{i=1}^{N} \left[(\alpha_{i}-1)^{2} + \beta_{i}^{2} + \gamma_{i}^{2} + (\delta_{i}-1)^{2} \right]$$

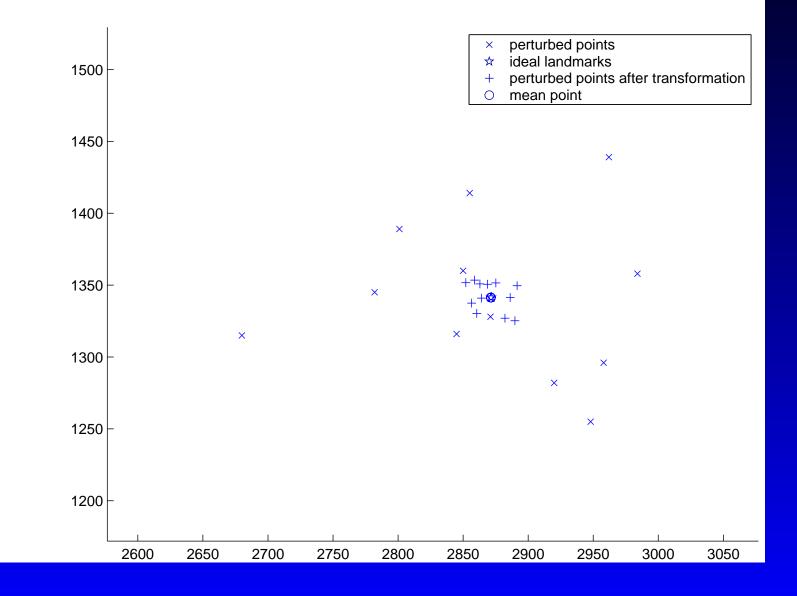
$$+\varphi_i^2 + \psi_i^2 + w \sum_{j=1}^M \left[(l_j^1 - m l_j^1)^2 + (l_j^2 - m l_j^2)^2 \right]$$

s.t.
$$-\epsilon_{ij} \leq \alpha_i l_{ij}^1 + \beta_i l_{ij}^2 + \varphi_i - l_j^1 \leq \epsilon_{ij}$$

 $-\epsilon_{ij} \leq \gamma_i l_{ij}^1 + \delta_i l_{ij}^2 + \psi_i - l_j^2 \leq \epsilon_{ij}$







• Statistical Modeling

Analysis of variance for spot volumes
 Mixed-effect model:

 fixed group effect
 random individual effect
 spatial correlation structure

Feature selection based on hypothesis testing of groups of wavelet coefficients